

**DCS\_SDK**

2.0.0

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# Chapter 1

## DCS-100 C++ SDK

This is a software development kit (SDK) for creating software that interacts with the Advanced illumination DCS-100E and DCS-103E devices. It is written using the 2011 ISO Standard for C++ (C++ 11).

### 1.1 Binary distribution

This release was compiled using the GNU toolchain version 9.3.0. Releases are available for Windows x86 and x64, and Linux x64.

See the [changelog](#) for more history.

### 1.2 Example Code

This example code queries each DCS device that is online and communicable, prints the ones it finds, and then connects to each and does the following:

For every channel:

- Sets channel to Continuous mode
- Pauses 200 milliseconds
- Sets the current on the channel to half of the light's continuous maximum
- Pauses 2 seconds
- Sets 0 current
- Sets the channel to Pulsed mode
- Sets the current on the channel to 1.2 A
- Sets pulse width to 10ms
- Sets pulse delay to 5us

- Sets trigger input to Input 3
- Pulses the light three times (500 ms between each)
- Sets the channel to 0 current

It then sets the device name to "Tested" and disconnects from the device.

```
#include "DCS100.h"
#include "DCS_Info.h"
#include <iostream>
#include <chrono>
#include <thread>
using namespace std;
namespace ai = AdvancedIllumination;
int main()
{
    auto list = ai::DCS_Info::findAllInNetwork(false);
    if(list.size() == 0) {
        cout << "No DCS units found.\n";
        return 0;
    }
    try
    {
        for (const ai::DCS_Info& dcs : list)
        {
            std::cout << "Found DCS: " << dcs.name() << " at " << dcs.host() << "\n";
            ai::DCS_100 device;
            device.connect(dcs.host());
            size_t N = device.ChannelCount();
            for (int i = 0; i < N; i++)
            {
                if (device[i].maxContinuous() == 0) continue;
                printf("Setting channel %d mode 1\n", i+1);
                device[i].mode(ai::Mode::Continuous);
                this_thread::sleep_for(chrono::milliseconds(200));
                double cc = 0.5*device[i].maxContinuous();
                printf("Setting channel %d current %.3f\n", i+1, cc);
                device[i].current(cc);
                this_thread::sleep_for(chrono::seconds(2));
                printf("Setting 0 current\n");
                device[i].current(0);
                printf("Setting strobe mode\n");
                device[i].mode(ai::Mode::Pulsed);
                printf("Setting 1.2A\n");
                device[i].current(1.2);
                printf("Setting PW 10ms\n");
                device[i].pulseWidth(10E-3);
                printf("Setting PD 5us\n");
                device[i].pulseDelay(5E-6);
                printf("Setting trigger input CH3\n");
                device[i].triggerInput(ai::Channel::Three);
                for (int j = 0; j < 3; j++)
                {
                    printf("(blink)\t");
                    device[i].trigger();
                    this_thread::sleep_for(chrono::milliseconds(500));
                }
                printf("\n");
                device[i].current(0);
                this_thread::sleep_for(chrono::milliseconds(500));
            }
            device.name("Tested");
            //device.ipAddress("10.1.103.50");
            device.webConfigEnabled(true);
            device.disconnect();
        }
    }
    catch (const ai::DeviceError& e)
    {
        cout << "Error: " << e.what() << "\n";
        return EXIT_FAILURE;
    }
    catch (const ai::DeviceWarning& e)
    {
        cout << "Warning: " << e.what() << "\n";
        return 1;
    }
    catch (const std::exception& e)
```

```
{  
    cout << "Exception: " << e.what() << "\n";  
    return 1;  
}  
return 0;  
}
```



## **Chapter 2**

# **Changelog**

### **2.1 1.0.0**

Initial release. Depended on POCO external libraries.

### **2.2 1.1.0**

Updated to support DCS-100E/103E RevA.

### **2.3 2.0.0**

Major revision, removes all external dependencies, builds as static library. Includes TinyXML 2 for XML parsing (compiled in).



# Chapter 3

## Namespace Index

### 3.1 Namespace List

Here is a list of all namespaces with brief descriptions:

<a href="#">AdvancedIllumination</a>	Namespace containing AI-created functions and classes . . . . .	15
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# Chapter 4

## Hierarchical Index

### 4.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

AdvancedIllumination::DCS_100 . . . . .	19
AdvancedIllumination::DCS_100::DCS_Channel . . . . .	28
AdvancedIllumination::DCS_Info . . . . .	34
invalid_argument	
AdvancedIllumination::DeviceWarning . . . . .	40
runtime_error	
AdvancedIllumination::DeviceError . . . . .	38



# Chapter 5

## Class Index

### 5.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">AdvancedIllumination::DCS_100</a>	Contains information and methods for working with DCS devices . . . . .	19
<a href="#">AdvancedIllumination::DCS_100::DCS_Channel</a>	Encapsulates the data related to a single DCS channel . . . . .	28
<a href="#">AdvancedIllumination::DCS_Info</a>	Class containing information about a DCS-100 device . . . . .	34
<a href="#">AdvancedIllumination::DeviceError</a>	An exception representing an error message from the device . . . . .	38
<a href="#">AdvancedIllumination::DeviceWarning</a>	An exception representing a warning message from the device . . . . .	40



# Chapter 6

## File Index

### 6.1 File List

Here is a list of all files with brief descriptions:

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## Chapter 7

# Namespace Documentation

## 7.1 AdvancedIllumination Namespace Reference

Namespace containing AI-created functions and classes.

### Classes

- class [DCS\\_100](#)  
*Contains information and methods for working with DCS devices.*
- class [DCS\\_Info](#)  
*Class containing information about a DCS-100 device.*
- class [DeviceError](#)  
*An exception representing an error message from the device.*
- class [DeviceWarning](#)  
*An exception representing a warning message from the device.*

### Enumerations

- enum [Mode](#) { [Mode::Off](#) = 0, [Mode::Continuous](#) = 1, [Mode::Pulsed](#) = 2, [Mode::Gated](#) = 3 }  
*Values that represent modes.*
- enum [Trigger](#) { [Trigger::Falling](#) = 0, [Trigger::Rising](#) = 1 }  
*Values that represent trigger edges (e.g.*
- enum [Channel](#) { [Channel::One](#) = 1, [Channel::Two](#) = 2, [Channel::Three](#) = 3 }  
*Values that represent channels.*
- enum [DCS\\_Type](#) { [DCS\\_Type::DCS\\_100E](#), [DCS\\_Type::DCS\\_103E](#) }  
*Values that represents the type of DCS connected.*

### 7.1.1 Detailed Description

Namespace containing AI-created functions and classes.

## 7.1.2 Enumeration Type Documentation

### 7.1.2.1 Channel

```
enum AdvancedIllumination::Channel [strong]
```

Values that represent channels.

#### Enumerator

One	The first channel.
Two	The second channel.
Three	The third channel.

### 7.1.2.2 DCS\_Type

```
enum AdvancedIllumination::DCS_Type [strong]
```

Values that represents the type of DCS connected.

#### Enumerator

DCS_100E	An enum constant representing the DCS-100E (single output, three channel) device.
DCS_103E	An enum constant representing the DCS-103E (three output, single channel per output) device.

### 7.1.2.3 Mode

```
enum AdvancedIllumination::Mode [strong]
```

Values that represent modes.

#### Enumerator

Off	An enum constant representing the "Off" mode.
Continuous	An enum constant representing the Continuous current mode.
Pulsed	An enum constant representing the Pulsed mode.
Gated	An enum constant representing the Gated mode.

#### 7.1.2.4 Trigger

```
enum AdvancedIllumination::Trigger [strong]
```

Values that represent trigger edges (e.g.

how each channel's triggering behaves).

##### Enumerator

Falling	A rising-edge trigger.
Rising	A falling-edge trigger.



# Chapter 8

## Class Documentation

### 8.1 AdvancedIllumination::DCS\_100 Class Reference

Contains information and methods for working with DCS devices.

```
#include <DCS100.h>
```

#### Classes

- class [DCS\\_Channel](#)  
*Encapsulates the data related to a single DCS channel.*

#### Public Member Functions

- [DCS\\_Channel & Channel](#) (size\_t)  
*Gets a channel by its number.*
- [DCS\\_Channel & operator\[\]](#) (size\_t)  
*Array indexer operator.*
- [const std::string & name](#) () const  
*Gets the name.*
- [void name](#) (const std::string &name)  
*Sets the name of the device.*
- [const std::string & firmwareVersion](#) () const  
*Gets the firmware version.*
- [const std::string & ipAddress](#) () const  
*Get the IP address.*
- [void ipAddress](#) (const std::string &ip)  
*Sets the device (static) IP address.*
- [size\\_t ChannelCount](#) () const  
*Gets the channel count of the device.*
- [const std::string & profileName](#) () const

- Gets the active profile name.
  - int [profileNumber \(\) const noexcept](#)  
Gets the active profile number.
  - void [profileName \(const std::string &\)](#)  
Sets the name of the active profile.
  - void [profileNumber \(int\)](#)  
Sets the active profile number.
  - void [webConfigEnabled \(const bool\)](#)  
Enable or disable the Web configuration interface.
  - bool [webConfigEnabled \(\) const](#)  
Determine if the Web configuration interface is enabled.
  - void [saveProfile \(\)](#)  
Saves the profile.
- [DCS\\_100 \(\)](#)  
Default constructor.
- [DCS\\_100 \(const char \\*ip\)](#)  
Creates an instance and connects to the given device.
- void [connect \(const std::string &ip\)](#)  
Connects to a DCS at the given IP address.
- void [disconnect \(\)](#)  
Disconnects this object from the physical DCS.
- void [refreshConfig \(\)](#)  
Refresh configuration from device.
- const std::vector< std::string > & [profileNames \(\) const](#)  
Gets the names of the saved profiles.
- [~DCS\\_100 \(\)](#)  
Destructor.
- void [refreshProfiles \(\)](#)  
Refresh profile names from device.

## Friends

- class [DCS\\_Channel](#)

### 8.1.1 Detailed Description

Contains information and methods for working with DCS devices.

### 8.1.2 Constructor & Destructor Documentation

### 8.1.2.1 DCS\_100() [1/2]

```
AdvancedIllumination::DCS_100::DCS_100 ( )
```

Default constructor.

### 8.1.2.2 DCS\_100() [2/2]

```
AdvancedIllumination::DCS_100::DCS_100 ( const char * device )
```

Creates an instance and connects to the given device.

#### Parameters

<i>device</i>	The device.
---------------	-------------

### 8.1.2.3 ~DCS\_100()

```
AdvancedIllumination::DCS_100::~DCS_100 ( )
```

Destructor.

## 8.1.3 Member Function Documentation

### 8.1.3.1 Channel()

```
DCS_100::DCS_Channel & AdvancedIllumination::DCS_100::Channel ( size_t i )
```

Gets a channel by its number.

This is the one-based (1-3) complement of the array index operator, which is zero-based.

#### Exceptions

<i>invalid_argument</i>	Thrown when <i>i</i> == 0 or <i>i</i> > 3 (if built with bounds checking) ( <a href="#">Third-party reference</a> )
-------------------------	---

**Parameters**

<i>i</i>	One-based index of the channel.
----------	---------------------------------

**Returns**

A reference to a [DCS\\_100::DCS\\_Channel](#): the channel.

### 8.1.3.2 ChannelCount()

```
size_t AdvancedIllumination::DCS_100::ChannelCount ( ) const
```

Gets the channel count of the device.

**Returns**

The number of active channels in the device.

### 8.1.3.3 connect()

```
void AdvancedIllumination::DCS_100::connect (
    const std::string & ip )
```

Connects to a DCS at the given IP address.

**Parameters**

<i>ip</i>	The IP address of the device to connect to
-----------	--

### 8.1.3.4 disconnect()

```
void AdvancedIllumination::DCS_100::disconnect ( )
```

Disconnects this object from the physical DCS.

Allows the DCS to communicate with other SDK or software instances.

### 8.1.3.5 **firmwareVersion()**

```
const string & AdvancedIllumination::DCS_100::firmwareVersion () const
```

Gets the firmware version.

#### Returns

A reference to a const string.

### 8.1.3.6 **ipAddress() [1/2]**

```
const string & AdvancedIllumination::DCS_100::ipAddress () const
```

Get the IP address.

#### Returns

The device IP address

### 8.1.3.7 **ipAddress() [2/2]**

```
void AdvancedIllumination::DCS_100::ipAddress (
    const std::string & ip )
```

Sets the device (static) IP address.

#### Exceptions

<i>invalid_argument</i>	Thrown when the IP address string is invalid. ( <a href="#">Third-party reference</a> )
<a href="#">DeviceWarning</a>	Thrown when the device response contains a warning.

#### Parameters

<i>ip</i>	The IP address to set (as a string).
-----------	--------------------------------------

### 8.1.3.8 **name() [1/2]**

```
const string & AdvancedIllumination::DCS_100::name () const
```

Gets the name.

#### Returns

The device name.

### 8.1.3.9 `name()` [2/2]

```
void AdvancedIllumination::DCS_100::name (
    const std::string & name )
```

Sets the name of the device.

#### Exceptions

<code>invalid_argument</code>	Thrown when the name string is invalid. ( <a href="#">Third-party reference</a> )
<code>DeviceWarning</code>	Thrown when the device issues a warning.

#### Parameters

<code>name</code>	The name to set. Cannot contain commas.
-------------------	---

### 8.1.3.10 `operator[]( )`

```
DCS_100::DCS_Channel & AdvancedIllumination::DCS_100::operator[] (
    size_t i )
```

Array indexer operator.

Provides access to the channels of the DCS.

#### Exceptions

<code>invalid_argument</code>	Thrown when index > 2 (if built with bounds checking). ( <a href="#">Third-party reference</a> )
-------------------------------	--

#### Parameters

<code>i</code>	Zero-based index of the channel to access.
----------------	--

**Returns**

The indexed channel.

**8.1.3.11 profileName() [1/2]**

```
const string & AdvancedIllumination::DCS_100::profileName () const
```

Gets the active profile name.

**Returns**

A reference to a const string.

**8.1.3.12 profileName() [2/2]**

```
void AdvancedIllumination::DCS_100::profileName (
    const std::string & name )
```

Sets the name of the active profile.

**Exceptions**

<i>DeviceWarning</i>	Thrown when a device warning error condition occurs.
<i>DeviceError</i>	Raised when a device error condition occurs.

**Parameters**

<i>name</i>	The name.
-------------	-----------

**8.1.3.13 profileNames()**

```
const std::vector< std::string > & AdvancedIllumination::DCS_100::profileNames () const
```

Gets the names of the saved profiles.

**Returns**

A reference to a const std::vector of strings containing the profile names.

**8.1.3.14 profileNumber() [1/2]**

```
int AdvancedIllumination::DCS_100::profileNumber ( ) const [noexcept]
```

Gets the active profile number.

**Returns**

A const int.

**8.1.3.15 profileNumber() [2/2]**

```
void AdvancedIllumination::DCS_100::profileNumber ( int num )
```

Sets the active profile number.

**Parameters**

<i>num</i>	The profile number (0-24) to set.
------------	-----------------------------------

**8.1.3.16 refreshConfig()**

```
void AdvancedIllumination::DCS_100::refreshConfig ( )
```

Refresh configuration from device.

**8.1.3.17 refreshProfiles()**

```
void AdvancedIllumination::DCS_100::refreshProfiles ( )
```

Refresh profile names from device.

**8.1.3.18 saveProfile()**

```
void AdvancedIllumination::DCS_100::saveProfile ( )
```

Saves the profile.

**8.1.3.19 webConfigEnabled() [1/2]**

```
bool AdvancedIllumination::DCS_100::webConfigEnabled ( ) const
```

Determine if the Web configuration interface is enabled.

**Returns**

A const bool, true for enabled and false for disabled.

**Remarks**

If the web configuration interface is enabled, a web browser may be directed to the [IP address](#) of the device.

**8.1.3.20 webConfigEnabled() [2/2]**

```
void AdvancedIllumination::DCS_100::webConfigEnabled (   
    const bool b )
```

Enable or disable the Web configuration interface.

**Parameters**

<i>b</i>	true for enabled, false for disabled.
----------	---------------------------------------

## 8.1.4 Friends And Related Function Documentation

### 8.1.4.1 DCS\_Channel

```
friend class DCS_Channel [friend]
```

The documentation for this class was generated from the following files:

- sdk/DCS100.h
- sdk/DCS100.cpp

## 8.2 AdvancedIllumination::DCS\_100::DCS\_Channel Class Reference

Encapsulates the data related to a single DCS channel.

```
#include <DCS100.h>
```

### Public Member Functions

- double **current** () const  
*Gets the current.*
- void **current** (const double)  
*Sets the current.*
- double **pulseWidth** () const  
*Gets the pulse width.*
- void **pulseWidth** (const double)  
*Sets the pulse width.*
- double **pulseDelay** () const  
*Gets the pulse delay.*
- void **pulseDelay** (const double)  
*Sets the pulse delay.*
- double **maxContinuous** () const  
*Gets the maximum continuous current (per string of LEDs).*
- const double **maxStrobe** () const  
*Gets the maximum strobe current (per string of LEDs).*
- Mode **mode** () const  
*Gets the mode the channel is in.*
- void **mode** (const Mode)  
*Sets the channels' Mode.*
- Trigger **triggerMode** () const  
*Gets the trigger mode (rising or falling edge).*
- void **triggerMode** (const Trigger)

*Sets the trigger mode.*

- [Channel triggerInput \(\) const](#)

*Gets the configured trigger input channel.*

- [void triggerInput \(const Channel\)](#)

*Sets the trigger input (e.g.*

- [double maxFrequency \(\) const](#)

*The maximum frequency (in Hertz) at which this channel can be triggered.*

- [void trigger \(\) const](#)

*Triggers this channel (acts as if a single hardware trigger occurred).*

## Friends

- class [DCS\\_100](#)

### 8.2.1 Detailed Description

Encapsulates the data related to a single DCS channel.

Allows getting and setting the device current, pulse width, etc.

### 8.2.2 Member Function Documentation

#### 8.2.2.1 current() [1/2]

```
double AdvancedIllumination::DCS_100::DCS_Channel::current ( ) const
```

Gets the current.

##### Returns

The current (in Amps).

#### 8.2.2.2 current() [2/2]

```
void AdvancedIllumination::DCS_100::DCS_Channel::current (
    const double cur )
```

Sets the current.

**Exceptions**

<i>DeviceWarning</i>	Thrown when a device warning error condition occurs.
<i>DeviceError</i>	Raised when a Device error condition occurs.
<i>runtime_error</i>	Raised when a runtime error condition occurs. ( <a href="#">Third-party reference</a> )

**Parameters**

<i>cur</i>	The current (in Amps).
------------	------------------------

**8.2.2.3 maxContinuous()**

```
double AdvancedIllumination::DCS_100::DCS_Channel::maxContinuous ( ) const
```

Gets the maximum continuous current (per string of LEDs).

**Returns**

The maximum continuous current (per string), in Amps.

**8.2.2.4 maxFrequency()**

```
double AdvancedIllumination::DCS_100::DCS_Channel::maxFrequency ( ) const
```

The maximum frequency (in Hertz) at which this channel can be triggered.

**Returns**

A const double; the maximum trigger frequency for this channel.

**8.2.2.5 maxStrobe()**

```
const double AdvancedIllumination::DCS_100::DCS_Channel::maxStrobe ( ) const
```

Gets the maximum strobe current (per string of LEDs).

**Returns**

The maximum strobe current (per string), in Amps.

### 8.2.2.6 mode() [1/2]

```
Mode AdvancedIllumination::DCS_100::DCS_Channel::mode () const
```

Gets the mode the channel is in.

#### Returns

The channel's Mode.

### 8.2.2.7 mode() [2/2]

```
void AdvancedIllumination::DCS_100::DCS_Channel::mode (
    const Mode )
```

Sets the channels' Mode.

#### Parameters

<i>m</i>	The Mode to set.
----------	------------------

### 8.2.2.8 pulseDelay() [1/2]

```
double AdvancedIllumination::DCS_100::DCS_Channel::pulseDelay () const
```

Gets the pulse delay.

#### Returns

The pulse delay (in seconds).

### 8.2.2.9 pulseDelay() [2/2]

```
void AdvancedIllumination::DCS_100::DCS_Channel::pulseDelay (
    const double pd )
```

Sets the pulse delay.

**Exceptions**

<code>std::invalid_argument</code>	Thrown when pulse delay exceeds 10 milliseconds. ( <a href="#">Third-party reference</a> )
------------------------------------	--

**Parameters**

<code>pd</code>	The pulse delay (in seconds).
-----------------	-------------------------------

**8.2.2.10 pulseWidth() [1/2]**

```
double AdvancedIllumination::DCS_100::DCS_Channel::pulseWidth () const
```

Gets the pulse width.

**Returns**

The pulse width (in seconds).

**8.2.2.11 pulseWidth() [2/2]**

```
void AdvancedIllumination::DCS_100::DCS_Channel::pulseWidth (
    const double pw )
```

Sets the pulse width.

Must be less than or equal to 65535 microseconds (0.065535 seconds)

**Exceptions**

<code>invalid_argument</code>	Thrown when pulse width exceeds 65535 microseconds. ( <a href="#">Third-party reference</a> )
<code>runtime_error</code>	Raised when a runtime error condition occurs. ( <a href="#">Third-party reference</a> )

**Parameters**

<code>pw</code>	The pulse width (in seconds).
-----------------	-------------------------------

### 8.2.2.12 trigger()

```
void AdvancedIllumination::DCS_100::DCS_Channel::trigger ( ) const
```

Triggers this channel (acts as if a single hardware trigger occurred).

### 8.2.2.13 triggerInput() [1/2]

```
Channel AdvancedIllumination::DCS_100::DCS_Channel::triggerInput ( ) const
```

Gets the configured trigger input channel.

#### Returns

A const Channel.

### 8.2.2.14 triggerInput() [2/2]

```
void AdvancedIllumination::DCS_100::DCS_Channel::triggerInput ( const Channel )
```

Sets the trigger input (e.g.

which hardware trigger input this channel is bound to).

#### Remarks

This function sets which hardware trigger input this channel responds to on trigger events. Any combination of channels can be set to any trigger input, however each channel can only be assigned to one hardware input. That is, all three channels on a DCS-100E can share trigger input 1, but channel one can't be triggered on inputs 1 and 2, only input 1 or 2 (not both).

#### Parameters

<i>chan</i>	The channel to which this channel's trigger will be assigned.
-------------	---

### 8.2.2.15 triggerMode() [1/2]

```
Trigger AdvancedIllumination::DCS_100::DCS_Channel::triggerMode ( ) const
```

Gets the trigger mode (rising or falling edge).

#### Returns

The channel's current trigger mode.

#### 8.2.2.16 triggerMode() [2/2]

```
void AdvancedIllumination::DCS_100::DCS_Channel::triggerMode ( const Trigger t )
```

Sets the trigger mode.

#### Exceptions

<i>DeviceWarning</i>	Thrown when a device warning error condition occurs.
<i>DeviceError</i>	Raised when a device error condition occurs.

#### Parameters

<i>t</i>	The trigger mode to set.
----------	--------------------------

### 8.2.3 Friends And Related Function Documentation

#### 8.2.3.1 DCS\_100

```
friend class DCS_100 [friend]
```

The documentation for this class was generated from the following files:

- sdk/DCS100.h
- sdk/DCS100.cpp

## 8.3 AdvancedIllumination::DCS\_Info Class Reference

Class containing information about a DCS-100 device.

```
#include <DCS_Info.h>
```

## Public Member Functions

- [DCS\\_Info \(\)](#)  
*Default constructor.*
- [~DCS\\_Info \(\)](#)  
*Destructor.*
- [const std::string & name \(\) const](#)  
*Gets the name of the device.*
- [const std::string & lighthead \(\) const](#)  
*Gets the part number of the connected lighthead.*
- [const std::string & firmware \(\) const](#)  
*Gets the firmware version.*
- [const std::string & host \(\) const](#)  
*Gets the host name (IP address) of the device.*
- [DCS\\_Type type \(\) const](#)  
*Gets the type of DCS.*

## Static Public Member Functions

- static [DCS\\_Info parse \(const std::string &idn, std::string host\)](#)  
*Parses the given IDN string.*
- static [std::vector< DCS\\_Info > findAllInNetwork \(bool global=false\)](#)  
*Searches for all online DCS devices in the network.*

### 8.3.1 Detailed Description

Class containing information about a DCS-100 device.

### 8.3.2 Constructor & Destructor Documentation

#### 8.3.2.1 DCS\_Info()

```
AdvancedIllumination::DCS_Info::DCS_Info ( )
```

Default constructor.

### 8.3.2.2 ~DCS\_Info()

```
AdvancedIllumination::DCS_Info::~DCS_Info ( )
```

Destructor.

## 8.3.3 Member Function Documentation

### 8.3.3.1 findAllInNetwork()

```
vector< DCS_Info > AdvancedIllumination::DCS_Info::findAllInNetwork ( bool global = false ) [static]
```

Searches for all online DCS devices in the network.

#### Parameters

<code>global</code>	Whether to use a global broadcast (255.255.255.255) or subnet (X.X.X.255)
---------------------	---

#### Returns

The found all in network.

### 8.3.3.2 firmware()

```
const std::string & AdvancedIllumination::DCS_Info::firmware ( ) const
```

Gets the firmware version.

#### Returns

The device firmware version.

### 8.3.3.3 host()

```
const std::string & AdvancedIllumination::DCS_Info::host () const
```

Gets the host name (IP address) of the device.

#### Returns

A reference to a const std::string, the device IP address.

### 8.3.3.4 lighthead()

```
const std::string & AdvancedIllumination::DCS_Info::lighthead () const
```

Gets the part number of the connected lighthead.

#### Returns

A reference to a const std::string. Empty if there is no light connected.

### 8.3.3.5 name()

```
const std::string & AdvancedIllumination::DCS_Info::name () const
```

Gets the name of the device.

#### Returns

The device name.

### 8.3.3.6 parse()

```
DCS\_Info AdvancedIllumination::DCS_Info::parse (
    const std::string & idn,
    std::string host ) [static]
```

Parses the given IDN string.

**Exceptions**

<i>invalid_argument</i>	Thrown when an invalid string is passed. ( <a href="#">Third-party reference</a> )
-------------------------	--

**Parameters**

<i>idn</i>	The IDN response string.
<i>host</i>	The host (IP address).

**Returns**

A [DCS\\_Info](#).

**8.3.3.7 type()**

[DCS\\_Type](#) AdvancedIllumination::DCS\_Info::type ( ) const

Gets the type of DCS.

**Returns**

A const DCS\_Type.

The documentation for this class was generated from the following files:

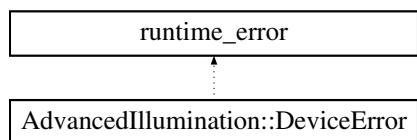
- sdk/[DCS\\_Info.h](#)
- sdk/[DCS\\_Info.cpp](#)

**8.4 AdvancedIllumination::DeviceError Class Reference**

An exception representing an error message from the device.

```
#include <DCS100.h>
```

Inheritance diagram for AdvancedIllumination::DeviceError:



## Public Member Functions

- virtual const char \* [what](#) () const noexcept  
*Gets the exception message.*
- [DeviceError](#) (const std::string msg)  
*Constructor.*
- virtual [~DeviceError](#) () noexcept  
*Destructor.*

### 8.4.1 Detailed Description

An exception representing an error message from the device.

### 8.4.2 Constructor & Destructor Documentation

#### 8.4.2.1 [DeviceError\(\)](#)

```
AdvancedIllumination::DeviceError::DeviceError (
    const std::string msg )
```

Constructor.

Creates an instance of the exception with the given message.

##### Parameters

<code>msg</code>	The message.
------------------	--------------

#### 8.4.2.2 [~DeviceError\(\)](#)

```
AdvancedIllumination::DeviceError::~DeviceError ( ) [virtual], [noexcept]
```

Destructor.

### 8.4.3 Member Function Documentation

#### 8.4.3.1 what()

```
const char * AdvancedIllumination::DeviceError::what () const [virtual], [noexcept]
```

Gets the exception message.

#### Returns

Null if it fails, else a pointer to a const char (C-string).

The documentation for this class was generated from the following files:

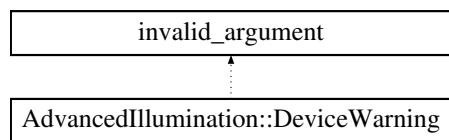
- sdk/DCS100.h
- sdk/DCS100.cpp

## 8.5 AdvancedIllumination::DeviceWarning Class Reference

An exception representing a warning message from the device.

```
#include <DCS100.h>
```

Inheritance diagram for AdvancedIllumination::DeviceWarning:



### Public Member Functions

- virtual const char \* [what](#) () const noexcept  
*Gets the exception message.*
- [DeviceWarning](#) (const std::string msg)  
*Constructor.*
- virtual [~DeviceWarning](#) () noexcept  
*Destructor.*

### 8.5.1 Detailed Description

An exception representing a warning message from the device.

### 8.5.2 Constructor & Destructor Documentation

#### 8.5.2.1 DeviceWarning()

```
AdvancedIllumination::DeviceWarning::DeviceWarning (   
     const std::string msg )
```

Constructor.

Creates an exception with the given message.

##### Parameters

<i>msg</i>	The message.
------------	--------------

#### 8.5.2.2 ~DeviceWarning()

```
AdvancedIllumination::DeviceWarning::~DeviceWarning ( ) [virtual], [noexcept]
```

Destructor.

### 8.5.3 Member Function Documentation

### 8.5.3.1 what()

```
const char * AdvancedIllumination::DeviceWarning::what ( ) const [virtual], [noexcept]
```

Gets the exception message.

#### Returns

Null if it fails, else a pointer to a const char (C-string).

The documentation for this class was generated from the following files:

- sdk/[DCS100.h](#)
- sdk/[DCS100.cpp](#)

# Chapter 9

## File Documentation

### 9.1 sdk/build/readme.md File Reference

### 9.2 sdk/changelog.md File Reference

### 9.3 sdk/DCS100.cpp File Reference

```
#include "DCS100.h"
#include "DCS_Info.h"
#include <cstdio>
#include "json.hpp"
#include "tinyxml2.h"
#include <regex>
#include <sstream>
#include <thread>
#include <chrono>
#include <unistd.h>
#include <sys/socket.h>
#include <sys/select.h>
#include <netinet/in.h>
#include <netinet/udp.h>
#include <arpa/inet.h>
```

## Namespaces

- [AdvancedIllumination](#)

*Namespace containing AI-created functions and classes.*

## Macros

- #define `sprintf_s` `sprintf`
- #define `SOCKET_ERROR` (-1)
- #define `INVALID_SOCKET` (-1)
- #define `MIN(a, b)` ((`a`) < (`b`) ? (`a`) : (`b`))

## Typedefs

- typedef int `Socket_t`
- using `json` = nlohmann::json

### 9.3.1 Macro Definition Documentation

#### 9.3.1.1 INVALID\_SOCKET

```
#define INVALID_SOCKET (-1)
```

#### 9.3.1.2 MIN

```
#define MIN(  
    a,  
    b ) ((a) < (b) ? (a) : (b))
```

#### 9.3.1.3 SOCKET\_ERROR

```
#define SOCKET_ERROR (-1)
```

#### 9.3.1.4 sprintf\_s

```
#define sprintf_s sprintf
```

### 9.3.2 Typedef Documentation

### 9.3.2.1 json

```
using json = nlohmann::json;
```

### 9.3.2.2 Socket\_t

```
typedef int Socket_t;
```

## 9.4 sdk/DCS100.h File Reference

```
#include <string>
#include <cinttypes>
#include <vector>
#include <iostream>
#include <exception>
```

### Classes

- class [AdvancedIllumination::DeviceWarning](#)  
*An exception representing a warning message from the device.*
- class [AdvancedIllumination::DeviceError](#)  
*An exception representing an error message from the device.*
- class [AdvancedIllumination::DCS\\_100](#)  
*Contains information and methods for working with DCS devices.*
- class [AdvancedIllumination::DCS\\_100::DCS\\_Channel](#)  
*Encapsulates the data related to a single DCS channel.*

### Namespaces

- [AdvancedIllumination](#)  
*Namespace containing AI-created functions and classes.*

### Macros

- #define [DCS\\_EXPORT](#)

## Enumerations

- enum `AdvancedIllumination::Mode` { `AdvancedIllumination::Mode::Off` = 0, `AdvancedIllumination::Mode::Continuous` = 1, `AdvancedIllumination::Mode::Pulsed` = 2, `AdvancedIllumination::Mode::Gated` = 3 }  
*Values that represent modes.*
- enum `AdvancedIllumination::Trigger` { `AdvancedIllumination::Trigger::Falling` = 0, `AdvancedIllumination::Trigger::Rising` = 1 }  
*Values that represent trigger edges (e.g.*
- enum `AdvancedIllumination::Channel` { `AdvancedIllumination::Channel::One` = 1, `AdvancedIllumination::Channel::Two` = 2, `AdvancedIllumination::Channel::Three` = 3 }  
*Values that represent channels.*

### 9.4.1 Macro Definition Documentation

#### 9.4.1.1 DCS\_EXPORT

```
#define DCS_EXPORT
```

## 9.5 sdk/DCS\_Info.cpp File Reference

```
#include "DCS_Info.h"
#include <string>
#include <regex>
#include "findpulsars.h"
#include <sstream>
```

## Namespaces

- `AdvancedIllumination`  
*Namespace containing AI-created functions and classes.*

## Functions

- std::string `getIPString` (uint32\_t ip)

### 9.5.1 Function Documentation

### 9.5.1.1 getIPString()

```
std::string getIPString (  
    uint32_t ip )
```

## 9.6 sdk/DCS\_Info.h File Reference

```
#include <vector>  
#include <string>  
#include "DCS100.h"
```

### Classes

- class [AdvancedIllumination::DCS\\_Info](#)  
*Class containing information about a DCS-100 device.*

### Namespaces

- [AdvancedIllumination](#)  
*Namespace containing AI-created functions and classes.*

### Macros

- [#define DCS\\_EXPORT](#)

### Enumerations

- enum [AdvancedIllumination::DCS\\_Type](#) { [AdvancedIllumination::DCS\\_Type::DCS\\_100E](#), [AdvancedIllumination::DCS\\_Type::DCS\\_100T](#) }  
*Values that represents the type of DCS connected.*

## 9.6.1 Macro Definition Documentation

### 9.6.1.1 DCS\_EXPORT

```
#define DCS_EXPORT
```



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